## $\Perp$ 凹 $\downarrow$ max planck institut

Informatics Campus

## A Verified SAT Solver with Watched Literals Using Imperative HOL

Peter
Lammich
$\pi \mathrm{m}$

Invent the Future

Mathias
Fleury
Jasmin C.
Blanchette

## SAT Solving

Given a formula in conjunctive normal form

$$
\varphi=\bigwedge_{i} \bigvee_{j} L_{i, j}
$$

is there an assignment making the formula true?

Most used algorithm: CDCL, an improvement over DPLL

## How reliable are SAT solvers？

Two ways to ensure correctness：
－certify the certificate
－certificates are huge
－verification of the code
－code will not be competitive
－allows to study metatheory

## I certify your proof <br>  <br> Isabelle Formalisation of Logic

## IsaFoL

- FO resolution by Schlichtkrull (ITP 2016)
- CDCL with learn, forget, restart, and incrementality by Blanchette, Fleury, Weidenbach (IJCAR 2016)
- GRAT certificate checker
by Lammich (CADE-26, 2017)
- A verified SAT solver with watched literals
by Fleury, Blanchette, Lammich (now)


## IsaFoL

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## Abstract CDCI

 Previous workWatched Titerals Calculus Transition system

## refines

Watched Titerals Algorithm Non-deterministic program


Refined SAT solver
Towards efficient data structures


Executable SAT solver
Standard MII

## Abstract CDCI <br> Previous work

## DPLL

Candidate model


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## Clause

1. $\neg \mathbf{B} \vee \mathbf{C} \vee \mathbf{A}$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
3. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4. $\neg \mathbf{A} \vee B$

## DPLL

## Candidate model

## $A^{?}$

1．$\neg \mathbf{B} \vee \mathbf{C} \vee \mathbf{A}$
2．$\neg \mathbf{C} \vee \neg B \vee \neg A$
3．$\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$

4．$\neg \mathbf{A} \vee B$

## Clause

1．Guess
2．or propagate information
3．or take the opposite of the last guess if there is a conflict

## DPLL

## Candidate model

## A? B

## 1. Guess

2. or propagate information
3. or take the opposite of the last guess if there is a conflict

## Clause

1. $\neg B \vee C \vee A$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
3. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4. $\neg \mathbf{A} \vee B$

## DBL

## Candidate model

## A？$\quad \mathrm{B} \boldsymbol{C}$

## 1．Guess

2．or propagate information
3．or take the opposite of the last guess if there is a conflict

## Clause

1．$\neg \mathbf{B} \vee C \vee A$
2．$\neg \mathbf{C} \vee \neg B \vee \neg A$
3．$\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4．$\neg \mathbf{A} \vee B$

## DPLL

Candidate model

## ᄀA

1. Guess
2. or propagate information
3. or take the opposite of the last guess if there is a conflict

## Clause

1. $\neg \mathbf{B} \vee \mathbf{C} \vee A$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
3. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4. $\neg \mathbf{A} \vee B$

## DPLL

## Candidate model

## $\neg A ~ \neg C ?$

## 1．Guess

2．or propagate information
3．or take the opposite of the last guess if there is a conflict

## Clause

1．$\neg \mathbf{B} \vee \mathbf{C} \vee \mathbf{A}$
2．$\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
3．$\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4．$\neg \mathbf{A} \vee B$

## DPLL

Candidate model

$$
\neg A \subset C ? ~ \neg B
$$

## 1. Guess

2. or propagate information
3. or take the opposite of the last guess if there is a conflict

## Clause

1. $\neg \mathbf{B} \vee C \vee A$
2. $\neg \mathbf{C} \vee \neg B \vee \neg \mathbf{A}$
3. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4. $\neg \mathbf{A} \vee B$

## DPLL

## Candidate model

## ᄀA

CDCL = DPLL + non-chronological backtracking + learning


1. $\neg \mathbf{B} \vee \mathbf{C} \vee \mathbf{A}$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
3. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4. $\neg \mathbf{A} \vee B$
5. ᄀA

## Propagate rule

C $\vee \mathrm{L} \in \mathrm{N} \Longrightarrow \mathrm{M}$ にas $\neg \mathrm{C} \Longrightarrow$ undefined_lit $\mathrm{M} L \Longrightarrow$ $(M, N) \Rightarrow \operatorname{CDCL}(L \# M, N)$

## Propagate rule

C $\vee \mathrm{L} \in \mathrm{N} \Longrightarrow \mathrm{M}$ にas $\neg \mathrm{C} \Longrightarrow$ undefined＿lit $\mathrm{M} \mathrm{L} \Longrightarrow$ $(M, N) \Rightarrow \operatorname{cocL}(L \# M, N)$

## Problem：

Iterating over the clauses is inefficient

Albstract CDCI
Previous work

## refines

## Watched Literals Calculus

Transition system

## refines

## Watched Titerals Algorithm

 Non-Deterministic program
## refines

Refined SAT solver
Towards efficient data structures


Executable SAT solver Standard MII

# Watched Iiterals Calculus 

## Transition system

## DPLL with Watched Literals

Candidate model

## 1．Watch one true lite 2．or watch two unse 3．or watch a false lite if all other literals IIII VirginiaTech

## DPLL with Watched Literals

Candidate model

## A?



1. $\neg \mathrm{B} \vee \mathrm{C}, ~ \mathrm{~A}$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
3. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4. $\neg \mathbf{A} \vee B$

To update:

## DPLL with Watched Literals

Candidate model

## A?

## Clause

1. $\neg \mathrm{B}, \mathrm{C}, ~ \mathrm{~A}$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
3. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4. $\neg A \cup B$

To update: 3. 4.

## DPLL with Watched Literals

Candidate model

## A?



1. $\neg \mathbf{B} \vee \mathrm{C}, ~ A$
2. $\neg \mathbf{C} \vee \neg \mathrm{B} \vee \mathrm{A}$
3. $\neg \mathbf{A} \vee \mathrm{B} \vee \mathrm{C}$
4. $\neg A$ B

To update:
4.

## DPLL with Watched Literals

Candidate model

## A?

## DPLL with Watched Literals

Candidate model

## $A^{?} \quad B$

## 1. Watch one true literals <br> 2. or watch two unset literals <br> 3. or watch a false literals <br> if all other literals are false



1. $\neg \mathrm{B} \vee \mathrm{C}, ~ \mathrm{~A}$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \mathrm{A}$
3. $\neg \mathrm{A} \vee \neg \mathrm{B} \cdot \mathrm{C}$
4. $\neg A$ B

To update:
B
ITI VirginiaTech

## DPLL with Watched Literals

Candidate model

## $A^{?} \quad B$



1. $\neg \mathrm{B} \vee \mathrm{C}, ~ \mathrm{~A}$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \mathrm{A}$
3. $\neg \mathrm{A} \vee \neg \mathrm{B} \cdot \mathrm{C}$
4. $\neg A$

To update: 1. 2.3.

## DPLL with Watched Literals

Candidate model

## $A^{?} \quad B$

1. Watch one true literals
2. or watch two unset literals
3. or watch a false literals
if all other literals are false

4. $\neg B \vee C D$
5. $\neg \mathbf{C} \vee \neg \mathrm{B} \vee \neg \mathrm{A}$
6. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
7. $\neg A$

To update:
2. 3.

## DPLL with Watched Literals

Candidate model

## $A^{?} \quad B$

1. Watch one true literals
2. or watch two unset literals
3. or watch a false literals
if all other literals are false

4. $\neg \mathbf{B} \vee \mathbf{C} \vee \mathbf{A}$
5. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
6. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
7. $\neg \mathbf{A} \vee B$

To update:
3.

## DPLL with Watched Literals

Candidate model

$$
\text { A? } \quad \mathrm{B} \quad \neg \mathrm{C}
$$

## 1. Watch one true literals

2. or watch two unset literals
3. or watch a false literals
if all other literals are false

4. $\neg \mathbf{B} \vee \mathbf{C} \vee \mathbf{A}$
5. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$

6. $\neg A$ B

To update:
3.

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## DPLL with Watched Literals

Candidate model

$$
\text { A? } \quad \mathrm{B} \quad \neg \mathrm{C}
$$

## 1. Watch one true literals

2. or watch two unset literals
3. or watch a false literals
if all other literals are false

4. $\rightarrow B \quad C \quad A$
5. $\neg \mathrm{C} \vee \neg \mathrm{B} \vee \neg \mathrm{A}$
6. $\neg \mathrm{A} \vee \neg \mathrm{B} \vee \mathrm{C}$
7. $\neg A$

To update:

## DPLL with Watched Literals

Candidate model

$$
\neg A
$$

To update:

$$
\neg A
$$

$$
\begin{aligned}
& \text { 1. } \neg \mathbf{B} \vee \mathbf{C} \vee \mathbf{A} \\
& \text { 2. } \neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A} \\
& \text { 3. } \neg \mathbf{A} \vee \neg \mathbf{\neg} \vee \mathbf{C} \\
& \text { 4. } \neg \mathbf{A} \vee \mathbf{B}
\end{aligned}
$$

## DPLL with Watched Literals

Candidate model

$$
\neg A
$$

1. Watch one true literals
2. or watch two unset literals
3. or watch a false literals
if all other literals are false

## Clause

1. $\neg \mathbf{B} \quad \mathbf{C} \vee \mathbf{A}$
2. $\neg \mathbf{C} \vee \neg \mathbf{B} \vee \neg \mathbf{A}$
3. $\neg \mathbf{A} \vee \neg \mathbf{B} \vee \mathbf{C}$
4. $\neg \mathbf{A} \vee B$
5. ᄀA

To update:

## Watched literals invariant

1．Watch one true literals
2．or watch two unset literals
3．or watch a false literals if all other literals are false

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## Watched literals invariant

1. Watch one true literals
2. or watch two unset literals
3. or watch a false literals if all other literals are false
unless a conflict has
been found

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## Watched literals invariant



VRIJE

## Watched literals invariant

(less wrong)


Finding invariants (11 new ones)

No high-level description
sledgehammer

Finding invariants (11 new ones)

No high-level description
sledgehammer

Correctness theorem
If $S$ is well-formed and $S \Rightarrow{ }_{\text {TwL }}!T$ then

$$
\mathrm{S} \Rightarrow \mathrm{CDCL}!\mathrm{T}
$$

## Abstract CDCI

Previous work

Watched Literals Calculus
Transition system

## refines

Watched Iriterals Algorithm
Non-deterministic Program
refines
Refined SAT solver
Towards efficient data structures

refines
Executable SAT solver Standard MIT

## Watched Iiterals Calculus

## Transition system

## 4

## Watched Iiterals Algorithm Non-deterministic Program

## Picking Next Clause

```
propagate_conflict_literal L S :=
    WHILET
    (\lambdaT. clauses_to_update T\not={})
    (\lambdaT. do {
        ASSERT(clauses_to_update T = {})
        C}\leftarrow\operatorname{SPEC ( }\lambda\textrm{C}.\textrm{C}\in\mathrm{ clauses_to_update T);
        U}\leftarrow\mathrm{ remove_from_clauses_to_update C T;
        update_clause (L, C) U
        }
    )
```

    S
    ```
propagate_conflict_literal L S :=
    WHILET
    (\lambdaT. clauses_to_update T = {})
    (\lambdaT. do {
        ASSERT(clauses_to_update T = {})
        C \leftarrow SPEC ( }\lambda\mathrm{ C. C E clauses_to_update T);
        U \leftarrowremove_from_clauses_to_update C T;
        update_clause (L, C) U
        }
    )
```

    S
    Refinement Framework: non-deterministic exception monad
propagate_conflict_literal LS := WHILE $_{T}$
( $\lambda$ T. clauses_to_update $T \neq\{ \}$ )
( $\lambda$ T. do \{
ASSERT(clauses_to_update $T \neq\{ \}$ )
$C \leftarrow$ SPEC ( $\lambda$ C. C $\in$ clauses_to_update $T$ );
$U \leftarrow$ remove_from_clauses_to_update C T; update_clause (L, C) U
\}
)

S

Refinement Framework: non-deterministic exception monad
propagate_conflict_literal LS := WHILE $_{T}$
( $\lambda$ T. clauses_to_update $T \neq\{ \}$ )
( $\lambda$ T. do \{
ASSERT(clauses_to_update $T \neq\{ \}$ )

Non-deterministic getting of a clause
$C \leftarrow S P E C(\lambda C . C \in$ clauses_to_update $T)$;
$U \leftarrow$ remove_from_clauses_to_update C T; update_clause (L, C) U
\}
)

S

```
propagate_conflict_literal L S :=
    WHILET
    (\lambdaT. clauses_to_update T = {})
    (\lambdaT. do {
        ASSERT(clauses_to_update T = {})
        C \leftarrow SPEC ( }\lambda\mathrm{ C. C E clauses_to_update T);
        U \leftarrowremove_from_clauses_to_update C T;
        update_clause (L, C) U
        }
    )
```

    S
    - More deterministic (order of the rules)
- But still non deterministic (decisions)
- Goals of the form
- More deterministic (order of the rules)
- But still non deterministic (decisions)
- Goals of the form

```
propagate_conflict_literal L S \leq SPEC(\lambdaT. S #TwL* T)
```


## VCG's goals hard to read

Very tempting to write fragile proofs
sledgehammer

## Albstract CDCI

## Previous work

## refines

Watched Titerals Calculus
Transition system

Watched Literals Algorithm
Non-deterministic Program


## Refined Styr Solver

Towards efficient data structures


Executable SAT solver Standard MII

## Watched Iiterals Algorithm Non－deterministic Program

## $\uparrow$

## Refined SATI Solver

## Towards efficient data structures

## DPLL with Watched Literals



To update：

A：$\neg A: 4 \quad$ C： $1,3 \neg C: 2$
B： $4 \neg$ B：1，2，3

```
propagate_conflict_literal L S :=
    WHILET
    (\lambdaT. clauses_to_update T = {})
    (\lambdaT. do {
        ASSERT(clauses_to_update T = {})
        C}\leftarrow\mathrm{ SPEC ( }\lambda\mathrm{ C. C & clauses_to_update T);
        U}\leftarrow\mathrm{ remove_from_clauses_to_update C T;
        update_clause LC U
        } propagate_conflict_literal_list L S :=
)
S
```

```
    WHILET
```

    WHILET
    (\lambda(w, T). w < length (watched_by T L))
    (\lambda(w, T). w < length (watched_by T L))
    (\lambda(w,T). do {
(\lambda(w,T). do {
C \leftarrow (watched_by T L)!w;
C \leftarrow (watched_by T L)!w;
update_clause_list L C T
update_clause_list L C T
}
}
)
)
(S, 0)

```
(S, 0)
```



0 - More new invariants
Aligning goals is hard...
Fast code uses many invariants
Forgotten and new invariants
sledgehammer
$0-\pi$ Choice on the heuristics
$0-\pi \quad$ Choice on the data structures
$0-\pi \quad$ Prepare code synthesis

## Decision heuristic

- Variable-move-to-front heuristic
- No correctness w.r.t. a standard implementation
- Behaves correctly:
- returns an unset literal if there is one
- no exception (out-of-bound array accesses)



## Refined SAFI Solver

## Towards efficient data structures

## $\uparrow$

## Executable SAF Solver

## Standard ML

sepref_definition executable_version
is <propagate_conflict_literal_heuristics〉
: : <unat_lit_assnk ${ }_{a}$ state_assnd $\rightarrow_{a}$ state_assn>
by sepref

Synthesise imperative code and a refinement relation

```
sepref_definition executable_version
    is <propagate_conflict_literal_heuristics>
    :: <unat_lit_assnk *a state_assnd }\mp@subsup{->}{a}{* state_assn>
    by sepref
```

Synthesise imperative code and a refinement relation

```
main_loop S :=
    heap_WHILET
            (\lambda(finished, _). return ( }\neg\mathrm{ finished))
            (\lambda(_, state).
            propagate state >>
            analyse_or_decide)
            (False, state) >>
(\lambda(_, final_state). return final_state)
```

sepref_definition executable_version
is <propagate_conflict_literal_heuristics>
: : <unat_lit_assnk ${ }_{a}$ state_assnd $\rightarrow_{a}$ state_assn>
by sepref

Synthesise imperative code and a refinement relation
fun main_loop state $=$

$$
\mathrm{fn}()=>
$$

let
val (_, final_state) $=$ heap_WHILET
(fn (done, _) $=>$ (fn () => not done))
(fn (_, state) $=>$
(analyse_or_decide (propagate state ()) ()))
(false, xi)
();
in final_state end;
sepref_definition executable_version
is <propagate_conflict_literal_heuristics>
: : <unat_lit_assnk ${ }^{*}$ a state_assnd $\rightarrow_{a}$ state_assn>
by sepref

Synthesise imperative code and a refinement relation

```
fun cdcl_twl_stgy_prog_wl_D_code x =
    (fn xi => fn () =>
    let
        val a =
    heap_WHILET (fn (a1, _) => (fn () => (not a1)))
        (fn (_, a2) =>
            (fn f_ => fn () => f_ ((unit_propagation_outer_loop_wI_D a2) ()) ())
            cdcl_twl_o_prog_wl_D_code)
            (false, xi) ();
        in
        let
            val (_, aa) = a;
        in
            (fn () => aa)
        end
            ()
```

$0-\pi$ Choice on the data structures
Clauses: resizable arrays of (fixed sized) arrays

However, no aliasing

- Indices instead of pointers
- N[C] makes a copy, so only use N[C][i]

Generates imperative code

No error messages

Transformations before generating code

## Clauses of length 0 <br> and 1

Once combined with an initialisation:

```
<(IsaSAT_code, model_if_satisfiable)
    \epsilon [\lambdaN. each_clause_is_distinct N ^
        literals_fit_in_32_bit_integer N]a
        clauses_as_listsk }->\mathrm{ model>
```

    in Isabelle
    Exported code tested with an unchecked parser (easy and medium problems from the SAT competition 2009)


Performance of the first executable version

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Performance of IsaSAT

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AMSTERDAM


Performance of IsaSAT

VRIJE



- better implementation (trail, conflict)
- dynamic decision heuristic

Abstract CDCI
Previous work

## refines

## Watched Initerals Calculus

 Transition system
## refines

## Watched Iriterals Algorithm

 Non－deterministic program －refines
## Refined StyT Solver

Towards efficient data structures

－better implementation（trail，conflict）
－dynamic decision heuristic
－learned clause minimisation
－allow learned clause minimisation

Executable SAT solver
Standard MII

Abstract CDCI
Previous work

## 4 refines

## Watched Literals Calculus

Transition system

## refines

Watched Titerals Algorithm Non-deterministic program 1 refines

## Refined Sty Solver

Towards efficient data structures
4 refines

## Executable SAT solver <br> Standard MIM

- allow learned clause minimisation
- more invariants
- better implementation (trail, conflict)
- dynamic decision heuristic
- learned clause minimisation


## How hard is it?

|  | Paper | Proof assistant |
| :---: | :---: | :---: |
| Very abstract | 13 pages | 50 pages |
| Abstract CDCL | 9 pages ( $1 / 2$ month) | 90 pages (5 months) |
| Watched Literals | $\begin{gathered} 1 \text { page } \\ (\mathrm{C}++ \text { code of } \\ \text { MiniSat) } \end{gathered}$ | 600 pages <br> (15 months) |

## Conclusion

## Concrete outcome

- Watched literals optimisation
- Verified executable SAT solver


## Methodology

- Refinement using the Refinement Framework

Future work

- Restarts
- Use SAT solver in IsaFoR
- SAT Modulo Theories (e.g., CVC or z3)


## Annex

```
for (i = j = 1; i < out_learnt.size(); i++)
    if (reason(var(out_learnt[i])) == CRef_Undef II
        !litRedundant(out_learnt[i]))
        out_learnt[j++] = out_learnt[i];
```

```
fun minimize_and_extract_highest_lookup_conflict_code x =
    (fn ai => fn bid => fn bic => fn bib => fn bia => fn bi => fn () =>
    let
            val a =
                heap_WHILET
                (fn (_, (a1a, (_, a2b))) =>
                (fn f_ => fn () => f_ ((length_arl_u_code heap_uint32 a2b) ()) ())
                    (fn x_a => (fn () => (Word32.< (a1a, x_a)))))
            (fn (a1, (a1a, (a1b, a2b))) =>
                (fn f_ => fn () => f_
                    (((fn () => Array.sub (fst a2b, Word32.tolnt a1a))) ()) ())
                    (fn x_a =>
                    (fn f_ => fn () => f_
                    ((literal_redundant_wl_lookup_code ai bid a1 a1b x_a bia) ())
                    ())
                            (fn (a1c, (_, a2d)) =>
                            (if not a2d
                        then (fn () =>
                            (a1, (Word32.+ (a1a, (Word32.fromlnt 1)),
                    (a1c, a2b))))
                    else (fn f_ => fn () => f_
                            ((delete_from_lookup_conflict_code x_a a1) ()) ())
                            (fn x_e =>
                            (fn f_ => fn () => f_ ((arl_last heap_uint32 a2b)
                    ()) ())
                            (fn xa =>
                                    (fn f_ => fn () => f_
                                    ((arl_set_u heap_uint32 a2b a1a xa) ()) ())
                                    (fn xb =>
                                    (fn f_ => fn () => f_
((arl_butlast heap_uint32 xb) ()) ())
(fn xc => (fn () => (x_e, (a1a, (a1c, xc))))))))))))
        (bic, ((Word32.fromInt 1), (bib, bi))) ();
    in
        let
            val (a1, (_, (a1b, a2b))) = a;
```


## What is in IsaSAT？

## Conflict Analysis

－conflict as lookup table（Minisat）
－and as explicit array（Minisat＇s＂out＂，to simplify proofs）
Decisions
－Variable move to front（Splatz，cadical）

## Propagations

－Mostly following MiniSAT（without BLIT）

## How much is missing?

- arena based memory allocation for clauses and watchers
- blocking literals (BLIT)
- special handling of binary clause watches
- literal-move-to-front watch replacement (LMTF)
- learned clause minimization with poison
- on-the-fly hyper-binary resolution (HBR)
- learning additional units and binary clauses (multiple UIPs)
- on-the-fly self-subsuming resolution (OTFS)
- decision only clauses (DECO)
- failed literal probing on binary implication graph roots
- eager recent learned clause subsumption

Thank you, Norbert \& Mate!

## Slides by Armin Biere

- stamping based VMTF instead of VSIDS
- subsumption for both irredundant and learned clauses
- inprocessing blocked clause decomposition (BCD) enabling ...
- ... inprocessing SAT sweeping for backbones and equivalences
- equivalent literal substitution (ELS)
- bounded variable elimination (BVE)
- blocked clause elimination (BCE)
- dynamic sticky clause reduction
- exponential moving average based restart scheduling
- delaying restarts
- trail reuse

Splatz @ POS'15

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## How much is missing?

## Features (I)

- arena based memory allocation for clauses and watchers
- blocking literals (BLIT)
- special handling of binary clause watches
- literal-move-to-front watch replacement (LMTF)
- learned clause minimization with poison
- on-the-fly hyper-binary resolution (HBR)
- learning additional units and binary clauses (multiple UIPs)
- on-the-fly self-subsuming resolution (OTFS)
- decision only clauses (DECO)
- failed literal probing on binary implication graph roots
- eager recent learned clause subsumption


## Splatz @ POS'15

## Code only

10

Thank you, Norbert \& Mate!

## Slides by Armin Biere

- stamping based VMTF instead of VSIDS
- subsumption for both irredundant and learned clauses
- inprocessing blocked clause decomposition (BCD) enabling ...
- ... inprocessing SAT sweeping for backbones and equivalences
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## How much is missing?

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## Code only

Strengthening
Change CDCL

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## Code only

Restarts (future)

## Strengthening

Change CDCL

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## Code only

Restarts (future)

## Strengthening

## Change WL

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Change CDCL

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## Splatz @ POS'15

## Code only

## Strengthening

## Restarts (future)

Change WL

## Slides by Armin Biere

```
- Unchecked array accesses (Isabelle takes care
    of it)
- No unbounded integers (in theory, not complete
        anymore)
    - Restarts
```

    - exponential moving average based restart scheduling
    - delaying restarts
    - trail reuse
    Change CDCL

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## Update Strategy

A first idea


A better strategy


## Update Strategy

A first idea


A better strategy


## A

B

C

## Update Strategy

A first idea


A


## Update Strategy

A first idea


A better strategy


## Update Strategy

A first idea


A better strategy


C

## Update Strategy

A first idea


A better strategy

c

## Update Strategy

A first idea

$B$

A better strategy


## A

$\square$
$\square$
$\square$

D

## Update Strategy

A first idea


B

A better strategy



## Update Strategy

A first idea


A better strategy



## Update Strategy

A first idea

$B$

A better strategy


B
$\square$

## Update Strategy

A first idea


B

A better strategy


